



LOW-VOLTAGE H-BRIDGE DRIVER

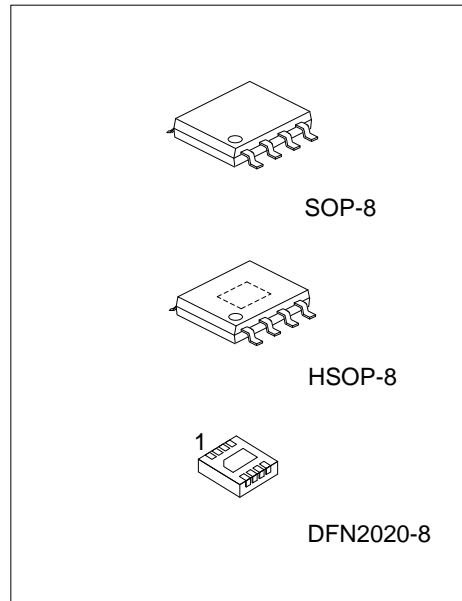
DESCRIPTION

The UTC **UMD9137** can supply up to 1.8 A of output current. It operates on a motor power supply voltage from 0 to 11 V, and a device power supply voltage of 1.8 V to 7.0 V.

The UTC **UMD9137** provides an integrated motor driver solution. The device can drive one DC motor or other devices like solenoids. The output driver block consists of N-channel power MOSFET's configured as an H-bridge to drive the motor winding. An internal charge pump generates needed gate drive voltages.

The UTC **UMD9137** has a PWM (IN1/IN2) input interface. Both interfaces are compatible with industry-standard devices.

Internal shutdown functions are provided for overcurrent protection, short circuit protection, undervoltage lockout, and overtemperature.



FEATURES

- * PWM Interface, IN1/IN2
- * Low-power Sleep Mode With 120-nA Maximum Sleep Current
 - nSLEEP pin
- * 1.8-A Maximum Drive Current
- * Separate Motor and Logic Supply Pins:
 - Motor V_M : 0~11 V
 - Logic V_{CC} : 1.8~7 V
- * Protection Features
 - V_{CC} Undervoltage Lockout
 - Overcurrent Protection
- * Thermal Shutdown

ORDERING INFORMATION

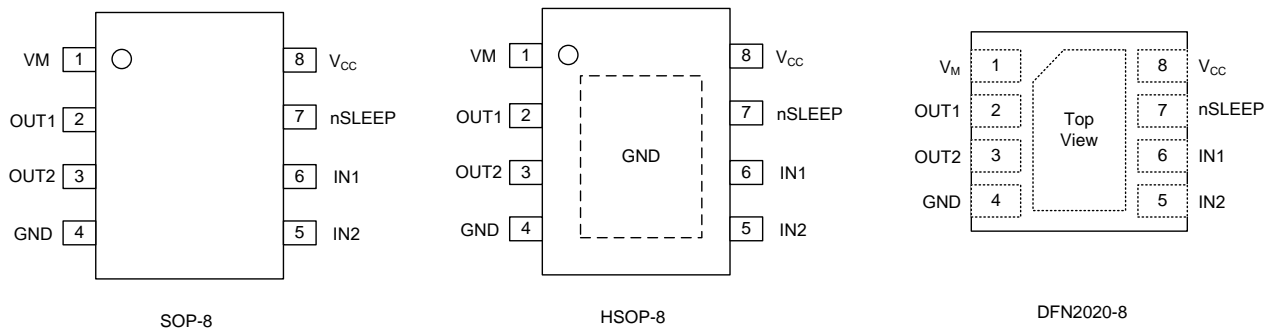
| Ordering Number | | Package | Packing |
|---------------------|---------------------|-----------|-----------|
| Lead Free | Halogen Free | | |
| UMD9137L-S08-R | UMD9137G-S08-R | SOP-8 | Tape Reel |
| UMD9137L-SH2-R | UMD9137G-SH2-R | HSOP-8 | Tape Reel |
| UMD9137L-K08-2020-R | UMD9137G-K08-2020-R | DFN2020-8 | Tape Reel |

| | |
|--|--|
| <p>UMD9137G-S08-R</p> <p>(1) Packing Type</p> <p>(2) Package Type</p> <p>(3) Green Package</p> | <p>(1) R: Tape Reel</p> <p>(2) S08: SOP-8, SH2: HSOP-8, K08-2020: DFN2020-8</p> <p>(3) G: Halogen Free and Lead Free, L: Lead Free</p> |
|--|--|

MARKING

| SOP-8 / HSOP-8 | DFN2020-8 |
|--|------------------------------|
| <p>UTC □□□□ → Date Code UMD9137 □□□□ → L: Lead Free G: Halogen Free □□□□ → Lot Code</p> | <p>9137 □□□□ → Date Code</p> |

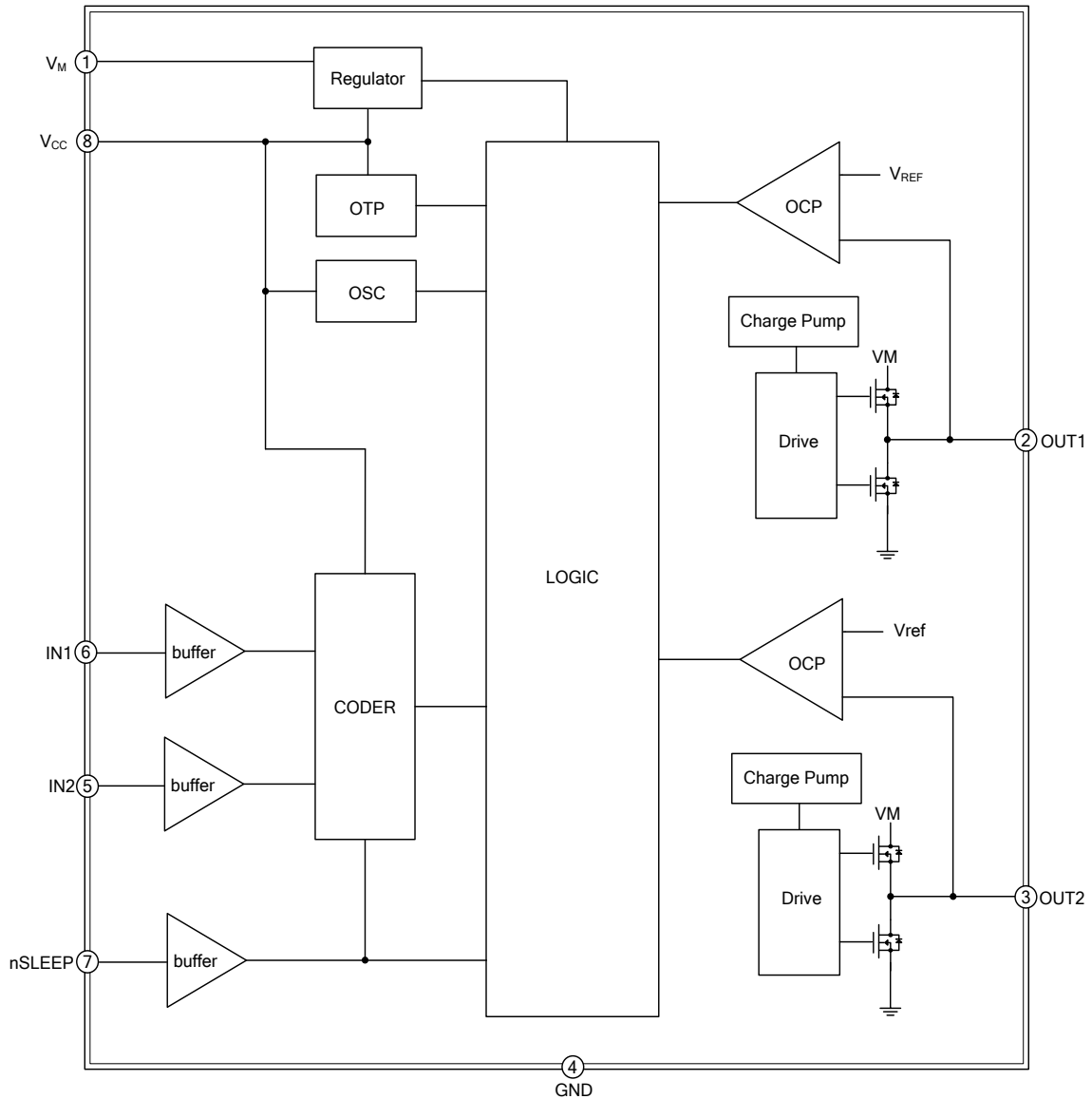
PIN CONFIGURATION



PIN DESCRIPTION

| PIN NO. | PIN NAME | DESCRIPTION |
|---------|-----------------|--------------------------|
| 1 | V _M | Motor power supply |
| 2 | OUT1 | Motor output |
| 3 | OUT2 | Connect to motor winding |
| 4 | GND | Device ground |
| 5 | IN2 | PHASE input |
| 6 | IN1 | |
| 7 | nSLEEP | Sleep mode input |
| 8 | V _{CC} | Logic Power supply |

■ BLOCK DIAGRAM



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■ ABSOLUTE MAXIMUM RATING

| PARAMETER | SYMBOL | RATINGS | UNIT |
|--|---------------------|--------------------|------|
| Motor Power Supply Voltage Range | V_M | 12 | V |
| Logic Power Supply Voltage Range | V_{CC} | 7 | V |
| Control Pin Voltage Range | IN1, IN2, nSLEEP | 7 | V |
| Peak Drive Current | OUT1, OUT2 | Internally limited | A |
| Operating Virtual Junction Temperature Range | T_J | -40 ~ +150 | °C |

Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

■ ELECTRICAL CHARACTERISTICS

($T_A = 25^\circ\text{C}$, over recommended operating conditions unless otherwise noted.)

| PARAMETER | SYMBOL | TEST CONDITION | MIN | TYP | MAX | UNIT |
|--|--------------|--|------|----------------------|-----|------|
| POWER SUPPLIES (V_M, V_{CC}) | | | | | | |
| V_M Operating Voltage | V_M | | | | 11 | V |
| V_M Operating Supply Current | I_{VM} | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ No PWM | | 40 | | uA |
| | | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ 50kHz PWM | | 0.8 | | mA |
| V_M Sleep Mode Supply Current | I_{VMQ} | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ nSLEEP=0 | | 30 | | nA |
| V_{CC} Operating Voltage | V_{CC} | | | | 7 | V |
| V_{CC} Operating Supply Current | I_{CC} | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ No PWM | | 300 | | uA |
| | | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ 50kHz PWM | | 0.7 | | mA |
| V_{CC} Sleep Mode Supply Current | I_{VCC} | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ nSLEEP=0 | | 5 | | nA |
| CONTROL INPUTS (IN1/PH, IN2/EN, nSLEEP) | | | | | | |
| Input Logic Low Voltage | V_{IL} | | | $0.38 \times V_{CC}$ | | V |
| Input Logic High Voltage | V_{IH} | | | $0.46 \times V_{CC}$ | | V |
| Input Logic Hysteresis | V_{HYS} | | | $0.08 \times V_{CC}$ | | mV |
| Input Logic Low Current | I_{IL} | $V_{IN} = 0\text{V}$ | -5 | | 5 | uA |
| Input Logic High Current | I_{IH} | $V_{IN} = 3.3\text{V}$ | | | 50 | uA |
| Pulldown Resistance | R_{PD} | | | 100 | | kΩ |
| MOTOR DRIVER OUTPUTS (OUT1, OUT2) | | | | | | |
| HS+LS FET On-Resistance | $R_{DS(ON)}$ | $V_M = 5\text{V}, V_{CC} = 3\text{V},$ $I_O = 800\text{mA}, T_J = 25^\circ\text{C}$ | | 280 | | mΩ |
| Off-state leakage current | I_{OFF} | $V_{OUT} = 0$ | -200 | | 200 | nA |
| PROTECTION CIRCUITS | | | | | | |
| V_{CC} Undervoltage Lockout | V_{UVLO} | V_{CC} falling | | | 1.7 | V |
| | | V_{CC} rising | | | 1.8 | V |
| Protection Trip Level | I_{OCP} | | 1.9 | | 3.5 | A |
| Overcurrent Deglitch Time | t_{DEG} | | | | | us |
| Overcurrent Retry Time | t_{RETRY} | | | | | ms |
| Thermal Shutdown Temperature | T_{TSD} | Die temperature T_J | | 160 | | °C |

■ TIMING REQUIREMENTS (T_A=25°C, V_M=5 V, V_{CC}=3 V, R_L=20 Ω)

| PARAMETER | TEST CONDITION | MIN | TYP | MAX | UNIT |
|-------------------|--|-----|-----|-----|------|
| t1 | Output enable time | | 300 | | ns |
| t2 | Output disable time | | 300 | | ns |
| t3 | Delay time, INx high to OUTx high | | 160 | | ns |
| t4 | Delay time, INx low to OUTx low | | 160 | | ns |
| t5 | Output rise time | | 188 | | ns |
| t6 | Output fall time | | 188 | | ns |
| t _{wake} | Wake time, nSLEEP rising edge to part active | | 30 | | us |

■ PRINCIPLE OF OPERATION

A low-power sleep mode is included, which can be enabled using the nSLEEP pin.

The UTC **UMD9137** is a H-bridge driver that can drive one DC motor or other devices like solenoids. The outputs are controlled using either a PWM interface (IN1/IN2) on the UTC **UMD9137**.

In addition, the UTC **UMD9137** adds protection features above traditional discrete implementations: undervoltage lockout, overcurrent protection, and thermal shutdown.

■ DESIGN REQUIREMENTS

Table 1 shows required parameters for a typical usage case.

Table 1. System Design Requirements

| DESIGN PARAMETER | REFERENCE | EXAMPLE VALUE |
|----------------------|------------------|---------------|
| Motor Supply Voltage | V _M | 9V |
| Logic Supply Voltage | V _{CC} | 3.3 V |
| Target RMS Current | I _{OUT} | 0.8 A |

■ FEATURE DESCRIPTION

Bridge Control

Table 2 shows the logic for the **UMD9137** device:

Table 2. System Design Requirements

| nSLEEP | IN1 | IN2 | OUT1 | OUT2 | Function (DC Motor) |
|--------|-----|-----|------|------|---------------------|
| 0 | X | X | Z | Z | Coast |
| 1 | 0 | 0 | Z | Z | Coast |
| 1 | 0 | 1 | L | H | Reverse |
| 1 | 1 | 0 | H | L | Forward |
| 1 | 1 | 1 | L | L | Brake |

Sleep Mode

If the nSLEEP pin is brought to a logic-low state, the UTC **UMD9137** enters a low-power sleep mode. In this state, all unnecessary internal circuitry is powered down.

Power Supplies

V_{CC} and V_M may be applied and removed in any order. When V_{CC} is removed, the device will enter a low power state and draw very little current from V_M .

The V_M voltage supply does not have any under voltage lockout protection (UVLO), so as long as $V_{CC} > 1.8$ V; the internal device logic will remain active. This means that the V_M pin voltage may drop to 0 V, however, the load may not be sufficiently driven at low V_M voltages.

Overcurrent Protection

An analog current limit circuit on each FET limits the current through the FET by removing the gate drive. Operation resumes automatically after tRETRY has elapsed. Overcurrent conditions will be detected on both the high-side and low-side devices.

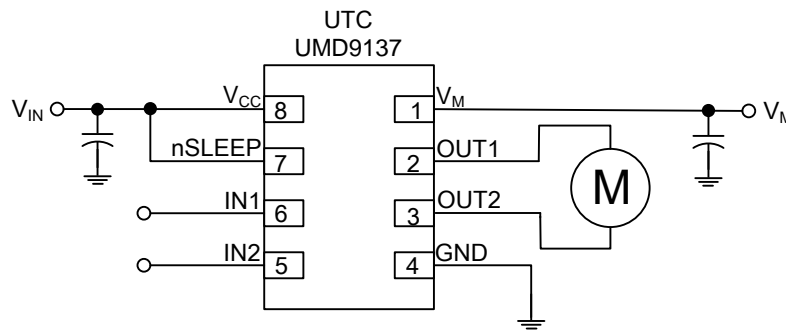
V_{CC} Undervoltage Lockout

If at any time the voltage on the V_{CC} pin falls below the under voltage lockout threshold voltage, all FETs in the H-bridge will be disabled. Operation resumes when V_{CC} rises above the UVLO threshold.

Thermal Shutdown

If the die temperature exceeds safe limits, all FETs in the H-bridge will be disabled. After the die temperature falls to a safe level, operation automatically resumes.

■ TYPICAL APPLICATION CIRCUIT



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